

Gaussian Processes

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Def. A collection of RVs $\{X_\alpha\}$ is said to be Gaussian if every finite linear combination,

$$\sum_{i=1}^n c_i X_{\alpha_i}$$

is a scalar Gaussian RV. We consider constants to be Gaussian RVs with zero variance.

If $X = [X_1, \dots, X_n]'$ is a random vector, then

$$\hat{m} := E[X] := [E[X_1] \dots E[X_n]]' \text{ is its mean}$$

vector, and

$$C := E[(X - \hat{m})(X - \hat{m})'] = [E[(X_i - m_i)(X_j - m_j)]]$$

is its covariance matrix.

Def. If $X = [X_1, \dots, X_m]'$ is Gaussian with mean m and covariance C , we write $X \sim N(m, C)$.

Prop. If $X \sim N(m, C)$ and $Y := AX + b$ for some matrix A and column vector b , then

$$Y \sim N(Am + b, ACA')$$

Prop If $X \sim N(m, C)$, then the characteristic function of X is

$$\phi_X(\nu) := E[e^{j\nu'X}] = e^{j\nu'm - \nu' C \nu / 2}$$

Proof. Since $X \sim N(m, C)$, $Y := \nu'X \sim N(\nu'm, \nu' C \nu)$
and so

$$E[e^{j\nu'X}] = E[e^{jY}] = E[e^{j\eta Y}] \Big|_{\eta=1}$$

$$= e^{j\eta m_Y - \eta^2 \sigma_Y^2 / 2} \Big|_{\eta=1}$$

$$= e^{j\nu'm - \nu' C \nu / 2} \quad \square$$

Corollary If X_1, \dots, X_n are ^{Gaussian &} uncorrelated, i.e.,
 $E[(X_i - m_i)(X_j - m_j)] = \sigma_i^2 \delta_{ij}$,
then X_1, \dots, X_n are independent.

Proof $\phi_X(\nu) = e^{j\nu'm - \nu' C \nu / 2}$

$$= e^{j \sum \nu_i m_i - \sum \sigma_i^2 \nu_i^2 / 2}$$

$$= \prod_{i=1}^n \underbrace{e^{j\nu_i m_i - \sigma_i^2 \nu_i^2 / 2}}_{N(m_i, \sigma_i^2)}$$

$$= \prod_{i=1}^n \phi_{X_i}(\nu) \quad \square$$

Prop If $Y \sim N(m, C)$ and C is invertible, then Y has a joint density,

$$f_Y(y) = \frac{\exp[-\frac{1}{2}(y-m)'C^{-1}(y-m)]}{(2\pi)^{n/2} \sqrt{\det C}}$$

Proof, Recall that $y = G(x)$ where G is invertible with inverse $H := G^{-1}$ so that $x = H(y)$, then

$$f_Y(y) = f_X(H(y)) | \det dH(y) |$$

where

$$dH(y) = \begin{bmatrix} \frac{\partial h_1}{\partial y_1} & \dots & \frac{\partial h_1}{\partial y_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial h_n}{\partial y_1} & \dots & \frac{\partial h_n}{\partial y_n} \end{bmatrix}$$

Put $X := C^{-1/2}(Y-m)$ so that $H(y) = C^{-1/2}(y-m)$ and $dH(y) = C^{-1/2}$. Next, we have to find $f_X(x)$. Observe that X is zero mean and

$$\begin{aligned} E[XX'] &= E[C^{-1/2}(Y-m)(Y-m)'C^{-1/2}] \\ &= C^{-1/2} C C^{-1/2} = I \end{aligned}$$

So, the components of X are uncorrelated.

Since Y is Gaussian, X is Gaussian. So the components of X are $\perp\!\!\!\perp N(0,1)$. Then

$$f_X(x) = \prod_{k=1}^n \frac{e^{-x_k^2/2}}{\sqrt{2\pi}} = \frac{e^{-x'x/2}}{(2\pi)^{n/2}}$$

We can now write,

$$f_Y(y) = \frac{e^{-[\bar{C}^{-1/2}(y-m)]' [\bar{C}^{-1/2}(y-m)] / 2}}{(2\pi)^{n/2}} \underbrace{|\det \bar{C}^{-1/2}|}_{= |(\det C)^{-1/2}|} \quad \square$$

The complex case. A complex RV $Z = X + jY$ is said to be continuous if X and Y are jointly continuous with joint density $f_{XY}(x, y)$.

We sometimes write

$$f_Z(z) := f_Z(x + jy) := f_{XY}(x, y).$$

Example $X, Y \perp\!\!\!\perp N(0, 1/2) \Rightarrow$

$$f_{XY}(x, y) = \frac{e^{-x^2}}{\sqrt{\pi}\sqrt{1/2}} \cdot \frac{e^{-y^2}}{\sqrt{\pi}\sqrt{1/2}} = \frac{e^{-|z|^2}}{\pi}$$

$$\underline{\text{Def}} \quad \text{var}(Z) := E[(Z - E[Z])(Z - E[Z])^*], \\ = \text{var}(X) + \text{var}(Y).$$

Example, If $Z = X + jY$ with $X, Y \perp\!\!\!\perp N(0, 1/2)$, then $\text{var}(Z) = 1$.

Def $Z = X + jY$ is a complex random vector ^{of dim. n} if

X and Y are real random vectors of dim. n . Also,

$$K := \text{cov}(Z) := E[(Z - E[Z])(Z - E[Z])^H].$$

$$K = (C_X + C_Y) + j(C_{YX} - C_{XY})$$

where $C_x := \text{cov}(X)$, $C_y = \text{cov}(Y)$, and

$$C_{xy} := \text{cov}(X, Y) := E[(X - m_x)(Y - m_y)']$$

If the $2n$ -dim vector $[X_1, \dots, X_n, Y_1, \dots, Y_n]'$ has joint density f_{xy} , we write

$$f_z(z) := f_{xy}(x_1, \dots, x_n, y_1, \dots, y_n)$$

Def. We say $Z = X + jY$ is Gaussian if the $2n$ -dim vector $[X', Y']'$ is Gaussian.

Def. A complex random vector $Z = X + jY$ is said to be circularly symmetric or proper if

$$C_x = C_y \quad \text{AND} \quad C_{xy} = -C_{yx}$$

Theorem. If an n -dim. complex Gaussian random vector $Z = X + jY$ is circularly symmetric with zero mean and covariance matrix K , then the chf of Z is

$$E[e^{j(\nu'X + \theta'Y)}] = e^{-w^H K w / 4}, \quad w := \nu + j\theta,$$

and if K is invertible,

$$f_{xy}(x, y) = \frac{e^{-z^H K^{-1} z}}{\pi^n \det K}, \quad z := x + jy.$$

Proof. omitted

Fact. If X_t is a Gaussian process; i.e., a family of Gaussian RVs, then

$$\int_a^b g(\tau) X_\tau d\tau$$

is a Gaussian RV. To see why this should be true, recall that this integral is defined as the limit in mean square of partial sums of the form

$$\sum_{i=1}^n g(\tau_i) X_{\tau_i} (\tau_i - \tau_{i-1}).$$

Since this is a linear combination of Gaussian RVs, the sum is Gaussian. Finally, the mean-square limit of Gaussian RVs is also Gaussian.

Using the above fact, it is easy to show that

$$Y_t = \int_a^b g(t, \tau) X_\tau d\tau$$

(#)

is a Gaussian process.

Def. The correlation function of a random process X_t is defined by

$$R(t, \tau) := E[X_t X_\tau^*].$$

Its covariance function is $C(t, \tau) := E[(X_t - m_t)(X_\tau - m_\tau)^*]$,

where $m_t := E[X_t]$. If $m_t = 0$, $C(t, \tau) = R(t, \tau)$.

If Y_t is given by ~~(#)~~,

$$\begin{aligned}
 R_{XY}(t, \tau) &:= E[X_t Y_\tau^*] \\
 &= E\left[X_t \int_a^b g(\tau, \theta) X_\theta^* d\theta\right] \\
 &= \int_a^b g(\tau, \theta) E[X_t X_\theta^*] d\theta \\
 &= \int_a^b g(\tau, \theta) R_X(t, \theta) d\theta
 \end{aligned}$$

(##)

Def We say X_t is white noise if $E[X_t] = 0$ and $R_X(t, \theta) = \sigma^2 \delta(t - \theta)$.

For white noise, ~~(##)~~ becomes

$$\begin{aligned}
 R_{XY}(t, \tau) &= \sigma^2 \int_a^b g(\tau, \theta) \delta(t - \theta) d\theta \\
 &= \begin{cases} \sigma^2 g(\tau, t)^* & t \in [a, b], \\ 0 & t \notin [a, b]. \end{cases}
 \end{aligned}$$

In general,

$$\begin{aligned}
 R_Y(t, \tau) &= E[Y_t Y_\tau^*] = E\left[\left(\int_a^b g(t, s) X_s ds\right) Y_\tau^*\right] \\
 &= \int_a^b g(t, s) E[X_s Y_\tau^*] ds \\
 &= \int_a^b g(t, s) R_{XY}(s, \tau) ds \\
 &= \int_a^b g(t, s) \left(\int_a^b g(\tau, \theta) R_X(s, \theta) d\theta\right) ds.
 \end{aligned}$$

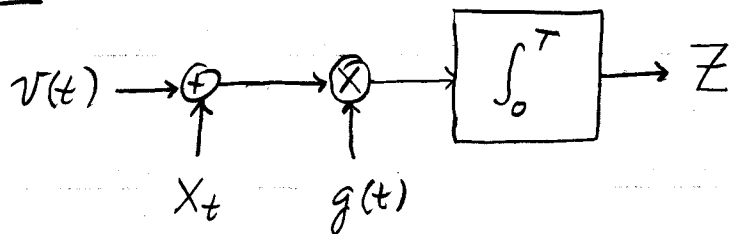
If X_t is white noise,

$$R_Y(t, \tau) = \sigma^2 \int_a^b g(t, s) g(\tau, s)^* ds.$$

In particular, if $Y = \int_a^b g(\tau) X_\tau d\tau$,

$$E[|Y|^2] = \sigma^2 \int_a^b |g(s)|^2 ds.$$

Application.



$$Z = \int_0^T g(t) [v(t) + X_t] dt = m + Y,$$

where $m := \int_0^T g(t) v(t) dt$ and $Y := \int_0^T g(t) X_t dt$.

If X_t is Gaussian white noise, then $Y \sim N(0, \sigma^2 \|g\|^2)$,

where $\|g\|^2 := \int_0^T |g(t)|^2 dt$. If $v(t) \equiv 0$, then

$$\begin{aligned} P(Z > \|g\|^2/2) &= Q\left(\frac{\|g\|^2/2}{\sigma \|g\|}\right) = Q\left(\frac{\|g\|}{2\sigma}\right) \\ &= Q\left(\sqrt{\frac{\|g\|^2}{4\sigma^2}}\right), \end{aligned}$$

where $Q(x) := \int_x^\infty \frac{e^{-t^2/2}}{\sqrt{2\pi}} dt$.

Craig's Formula

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Let $X \sim N(0, 1)$ and put

$$Q(x_0) := P(X > x_0) = \int_{x_0}^{\infty} \frac{e^{-x^2/2}}{\sqrt{2\pi}} dx$$

Then

$$Q(x_0) = \frac{1}{\pi} \int_0^{\pi/2} \exp\left(\frac{-x_0^2}{2\cos^2\theta}\right) d\theta, \quad x_0 \geq 0, \quad (*)$$

$$= \frac{1}{\pi} \int_0^{\pi/2} \exp\left(\frac{-x_0^2}{2\sin^2 t}\right) dt, \quad x_0 \geq 0. \quad (**)$$

Eq $(**)$ is Craig's formula. To derive $(*)$, write

$$P(X > x_0) = P(X > x_0, Y \in \mathbb{R}) = P((X, Y) \in D)$$

where $D := \{(x, y) : x > x_0\}$, Evaluate if $X \perp\!\!\!\perp Y$
with $Y \sim N(0, 1)$.

Application. Let V be a RV with MGF $M_V(s) = E[e^{sV}]$.

Then

$$E[Q(\sqrt{V})] = E\left[\frac{1}{\pi} \int_0^{\pi/2} \exp\left(\frac{-V}{2\sin^2 t}\right) dt\right]$$

$$= \frac{1}{\pi} \int_0^{\pi/2} E\left[e^{sV}\right] dt, \quad s = \frac{-1}{2\sin^2 t}$$

$$= \frac{1}{\pi} \int_0^{\pi/2} M_V\left(\frac{-1}{2\sin^2 t}\right) dt$$

$$= \frac{1}{\pi} \int_0^1 M_V\left(\frac{-1}{2\theta^2}\right) \frac{d\theta}{\sqrt{1-\theta^2}}$$

$$= \frac{1}{2\pi} \int_{-1}^1 M_V\left(\frac{-1}{2\theta^2}\right) \frac{d\theta}{\sqrt{1-\theta^2}}$$

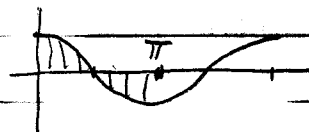
We can approximate this last integral using Chebyshev-Gauss quadrature. Thus,

$$E[Q(\sqrt{V})] \approx \frac{1}{2\pi} \sum_{k=1}^n w_k M_V\left(\frac{-1}{2\theta_k^2}\right), \quad (*)$$

where $\theta_k = \cos\left(\frac{2k-1}{2n}\pi\right)$, $k=1, \dots, n$,

and

$$w_k = \pi/n, \quad k=1, \dots, n.$$



Now, observe that $\theta_k = 0 \Leftrightarrow \frac{2k-1}{n} \cdot \frac{\pi}{2} = \text{odd} \cdot \frac{\pi}{2}$, which is impossible if n is even. So for even n , we do not have to worry about $\lim_{s \rightarrow -\infty} M_V(s)$.

Using the trig. identity $\cos(A-B) = \cos A \cos B + \sin A \sin B$, we see that

$$\theta_{n-l} = -\theta_{l+1} \quad \text{for } l=0, \dots, n-1.$$

If n is even,

$$\theta_n = -\theta_1$$

$$\theta_{n-1} = -\theta_2$$

$$\vdots$$

$$\theta_{n-\lfloor \frac{n}{2} \rfloor} = -\theta_{\frac{n}{2}}$$

If n is odd

$$\theta_n = -\theta_1$$

$$\theta_{n-1} = -\theta_2$$

$$\vdots$$

$$\theta_{n-\frac{n-1}{2}} = -\theta_{\frac{n+1}{2}} = 0,$$

and $(*)$ becomes for even n

$$\frac{1}{n} \sum_{k=1}^{n/2} M_V\left(\frac{-1}{2\theta_k^2}\right).$$