

## The Probability of Error for Binary Signaling over Multipath Channels

Pe-1

When the waveform  $\xi(t)$  is transmitted over a multipath channel with delays  $T_k$  and gains  $G_k$ , the response of the channel is

$$\hat{\xi}(t) := \sum_k G_k \xi(t - T_k)$$

If a receiver attempts to measure this during the time interval  $[0, T]$ , the received waveform is\*

$$r(t) = \hat{\xi}(t) + W_t, \quad 0 \leq t \leq T,$$

where  $W_t$  is AWGN with correlation function  $\sigma^2 \delta(t - \tau)$ .

If the delays and gains are known at the receiver, and binary signaling is used, say waveforms  $\xi_i(t)$ ,  $i=0,1$ , then the prob. of error is

$$Q\left(\sqrt{\frac{d^2}{4\sigma^2}}\right),$$

where

$$d^2 = \int_0^T |\hat{\xi}_1(t) - \hat{\xi}_0(t)|^2 dt = \int_0^T \left| \sum_k G_k \{ \xi_1(t - T_k) - \xi_0(t - T_k) \} \right|^2 dt$$

We now assume that the  $\xi_i$  are short-duration pulses on  $[0, t_p]$ , where  $t_p \ll T$ . Hence,

\* We assume  $\xi(t)$ ,  $G_k$ , and  $W_t$  are real.

$$\xi_{\Delta}(t) := \xi_1(t) - \xi_0(t)$$

is zero for  $t \notin [0, t_p]$ . We can then write

$$\begin{aligned} \hat{d}^2 &= \int_0^T \left| \sum_k G_k \xi_{\Delta}(t - T_k) \right|^2 dt \\ &= \sum_k \sum_l G_k G_l \int_0^T \xi_{\Delta}(t - T_k) \xi_{\Delta}(t - T_l) dt \\ &= \sum_k \sum_l G_k G_l \mathbb{I}_{[0, t_p]}(|T_l - T_k|) \int_0^T \xi_{\Delta}(t - T_k) \xi_{\Delta}(t - T_l) dt. \end{aligned}$$

If  $t_p$  is small enough that the probability of  $|T_l - T_k| \leq t_p$  is negligible for all  $l \neq k$ , then

$$\begin{aligned} \hat{d}^2 &\approx \sum_k G_k^2 \int_0^T |\xi_{\Delta}(t - T_k)|^2 dt \\ &= \underbrace{\sum_k G_k^2 \mathbb{I}_{[0, T]}(T_k)}_{=: \Phi} \int_{T_k}^{\min(T_k + t_p, T)} |\xi_{\Delta}(t - T_k)|^2 dt. \\ &=: \Phi \end{aligned}$$

When  $T_k \leq T - t_p$ , this last integral is  $\int_0^{t_p} |\xi_{\Delta}(\tau)|^2 d\tau =: d^2$ , which is the square of the distance between  $\xi_1$  and  $\xi_0$ . If the prob. that  $T_k \in [T - t_p, T]$  is negligible\*, then

$$\hat{d}^2 \approx \Phi \cdot d^2,$$

and the prob. of error is approximately

\*Or if  $G_k$  is negligible for  $T_k > T - t_p$ ; or if  $T = \infty$ .

$$Q\left(\sqrt{\frac{d^2\Phi}{4\sigma^2}}\right)$$

The average bit-error prob. is approximately

$$E\left[Q\left(\sqrt{\frac{d^2\Phi}{4\sigma^2}}\right)\right].$$

Recall Craig's formula,

$$\begin{aligned} Q(x) &= \frac{1}{\pi} \int_0^{\pi/2} \exp\left[\frac{-x^2}{2\sin^2 t}\right] dt \\ &= \frac{1}{\pi} \int_0^1 \frac{\exp\left[\frac{-x^2}{2y^2}\right]}{\sqrt{1-y^2}} dy \\ &= \frac{1}{2\pi} \int_{-1}^1 \frac{\exp(-x^2/(2y^2))}{\sqrt{1-y^2}} dy. \end{aligned}$$

Put

$$\begin{aligned} P_T(\gamma) &:= E\left[Q\left(\sqrt{2\gamma\Phi}\right)\right] \\ &= \frac{1}{2\pi} \int_{-1}^1 \frac{E\left[e^{-2\gamma\Phi/(2y^2)}\right]}{\sqrt{1-y^2}} dy \\ &= \frac{1}{2\pi} \int_{-1}^1 \frac{M(-\gamma/y^2)}{\sqrt{1-y^2}} dy, \end{aligned}$$

where  $M(\theta) := E[e^{\theta\Phi}]$ ,  $\theta \leq 0$ . Then the average BEP is approximately  $P_T(d^2/(8\sigma^2))$ .

Now, we can approximate  $P_T(\eta)$  using Chebyshev-Gauss quadrature to write

$$P_T(\eta) \approx \frac{1}{K} \sum_{k=1}^{K/2} M(-\eta/y_k^2),$$

where  $K$  is even and  $y_k := \cos\left(\frac{2k-1}{2K}\pi\right)$ ,  $k=1, \dots, K$ .

Example. If  $G_k=1$  for all  $k$  and the  $T_k$  are the arrival times of a Poisson process, then\*

$$\Phi = \sum_k I_{[0, T]}(T_k) = N_T \sim \text{Poisson}$$

with parameter  $\Lambda([0, T]) = \int_0^T \lambda(\tau) d\tau$ . Thus,

$$M(\theta) = E[e^{\theta N_T}] = e^{\Lambda([0, T])(e^\theta - 1)}$$

If the  $G_k$  are random, we need another approach.

\* If  $\Phi = N_T$ ,  $P_\Phi(\eta) = \sum_{n=0}^{\infty} Q(\sqrt{2\eta^n}) \frac{\Lambda([0, T])^n}{n!} e^{-\Lambda([0, T])}$